Engineering Applications

Ch. 8

Engineering Applications

Examples of practical problems that require solutions for implicit variables (I.e., an algebraic solution is not possible)

• Fluid Mechanics – Moody Diagram – Colebrook formula for determining friction factors is pipe flow

$$\frac{1}{f^{0.5}} = -2.0\log\left(\frac{e/D}{3.7} + \frac{2.51}{\text{Re } f^{0.5}}\right)$$

Using successive substitution, recast the equation:

$$f_{i+1} = \left(-2.0\log\left(\frac{e/D}{3.7} + \frac{2.51}{\text{Re }f_i^{0.5}}\right)\right)^{-2}$$

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 $2.\ \underline{Thermodynamics}-Ideal\ gas\ specific\ heats$

$$C_p = a + bT + cT^2 + dT^3$$

T = absolute temperature (K)

 C_p = Specific heat (KJ/kmol-K)

• Determine the temperature for which Cp=35.0 KJ/kmol-K.

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2. <u>Thermodynamics</u> – Ideal gas specific heats

$$f(T) = a + bT + cT^{2} + dT^{3} - C_{p} = 0$$

$$f(T) = 25.48 + 1.52 \times 10^{-2} T - 0.7155 \times 10^{-5} T^{2} + 1.312 \times 10^{-9} T^{3} - 35.0 = 0$$

If we use the **Newton-Raphson** Technique we need f'(x)

$$f'(T) = 1.52 \times 10^{-2} - 1.43 \times 10^{-5} T + 3.936 \times 10^{-9} T^2 = 0$$

$$T_{i+1} = T_i - \frac{f(T_i)}{f'(T_i)}$$

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3. <u>Vibration Analysis</u> – Linear Dynamic Systems

$$m\ddot{x} + c\dot{x} + kx = F(t)$$

$$x(t) = e^{rt} \longrightarrow Assume exponential solution$$

$$\dot{x}(t) = re^{rt}$$

$$\ddot{x}(t) = re^{rt}$$



Characteristic Equation for the Homogeneous problem

$$mr^2 + cr + k = 0$$